

CLAIMS (as originally filed and published)

1. A process for object detection, with the steps:
- enlarged optical imaging of at least one resting or moving object (10) on a structured mask (20) with at least one segment (30) which is adapted for transmitting light from a flat section (80), in which the object (10) is located at least partially or temporarily and which has a characteristic dimension smaller than the dimension of the object (10) or its movement path, to a detector unit (123),
 - detection of the quantity of light transmitted by the structured mask (20) and generation of a detector signal which has a predetermined relationship with the quantity of light, and
 - evaluation of the detector signal in regard to the presence of the object (10), its position, its shape, and/or the temporal change of the position.
2. The process according to claim 1, wherein the object detection is performed on synthetic or biological particles (10) in a microchannel of a fluidic microsystem in which the particle is subjected to hydrodynamic, acoustic, magnetic, and/or electrical forces.
3. The process according to claim 2, wherein the mask (20) is positioned in relation to the microsystem in such a way that light is transmitted by the mask from a section (80) in which the particle (10) is to be positioned or moved.
4. The process according to claim 2, wherein the mask (20) is positioned in relation to the microsystem in such a way that light is transmitted by the mask from

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15. The device according to claim 13 or 14, wherein cross-shaped segments, frame-shaped segments, and/or straight or curved strip-shaped segments are provided.
16. The device according to one of the claims 10 to 15, wherein the detector unit (123) is set up for integrated detection of the partial image of the object (10) or its movement path transmitted or reflected by the mask (20).
17. The device according to one of the claims 10 to 16, which is set up for object detection of synthetic or natural particles (10) in a fluidic microsystem.
18. The device according to claim 17, wherein the particles (10) in the microsystem are subjected to hydrodynamic, acoustic, magnetic, and/or electrical forces.
19. The device according to claim 17 or 18, wherein a trapping laser arrangement (60, 160) is provided for manipulation of the particles (10) in the microsystem.
20. The device according to one of the claims 10 to 19, wherein the segment (30) has a characteristic dimension which is smaller than the object (10) or its movement path or is smaller than the image of the object (10) or its movement path.
21. The use of a process or device according to one of the preceding claims for
- dielectric single particle spectroscopy in fluidic microsystems,
 - measurement of electromagnetic forces in microelectrode arrangements,
 - measurement of optical forces in trapping lasers,
 - detection of the function of microelectrodes in microsystems,

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